### **RNNs**

#### Recurrent Neural Networks

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ML 2 BDA3321

## Computational Graphs

### Node

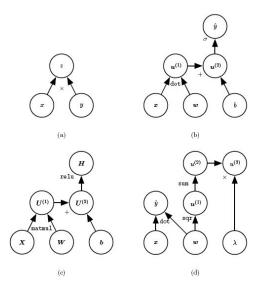
In our graphs, each node will indicate a variable.

### Operation

An operation is a function that returns a single value variable.

# Computational Graphs

### Examples



Consider the dynamic system

$$s^{(t)} = f(s^{t-1}; \theta)$$

For three steps, we get:

$$s^{(3)} = f(s^{(2)}; \theta) = f(f(s^{(1)}; \theta))$$

This can be represented graphically as

[lan17]

Consider a dynamic system driven by an external signal  $x^{(t)}$ :

$$s^{(t)} = f(s^{(t-1)}, x^{(t)}; \theta)$$

This can be used to define an RNN.

### **RNNs**

#### Recurrent Networks

$$h^{(t)} = f(h^{(t-1)}, x^{(t)}; \theta)$$

Representing the unfolded recurrence after t steps with a function  $g^{(t)}$ :

$$h^{(t)} = g^{(t)}(x^{(t)}, x^{(t-1)}, \dots, x^{(2)}, x^{(1)})$$
$$= f(h^{(t-1)}, x^{(t)}; \theta)$$

### References I

- [Mur12] Kevin P Murphy. *Machine Learning: A Probabilistic Perspective*. MIT Press, 2012.
- [Mar14] Stephen Marsland. *Machine Learning, An Algorithmic Perspective*. CRC Press, 2014.
- [Ian17] Aaron Courville Ian Goodfellow Yoshua Bengio. *Deep Learning*. MIT Press, 2017.